

D-80N

Intelligent Black Light Full-Color Night Vision Spherical Pod



Characteristics

- Carries a 40x hybrid zoom camera with ultra-starlight image sensor, combined with the AI-ISP full-color night vision imaging engine, can present clear full-color images in extremely low-light environments, delivering night vision-level low-light imaging experience. Featuring AI-HDR, it ensures both highlights and shadow details remain vividly visible even in complex lighting scenarios with extreme brightness contrasts.
- NIR laser lighting ensures the camera getting a clear image even in complete darkness.
- Features AI multi-object detection and tracking, which can constantly track one of the persons and vehicles intelligently identified in the image.
- Low-profile spherical shape and 3-axis nonorthogonal mechanical stabilized structure, minimize the gyration radius and the wind resistance of the pod. The gimbal is able to spin continually around its yaw axis.
- Supports network, UART and S.BUS control and compatible with both private protocol and MAVLink protocol.
- Thanks to the Dual-IMU complementary algorithms with IMU temperature control and carrier AHRS fusion, the gimbal provides a stabilization accuracy at $\pm 0.01^\circ$.
- Can be mounted onto multiple carriers, whether downward or upward.
- With the Dragonfly software, user can watch the image and control the pod without protocol ducking, and download photos and videos online as well.
- With the XF-QGC software, all the functions of the pod can be achieved in conjunction with an open source autopilot.
- Screen supports overlaying OSD information. Image supports EXIF saving. Live video stream and recording supports SEI saving. (The SEI functionality will be supported via subsequent firmware updates)
- 20~53 VDC wide voltage input.

Specifications

| General | |
|---------------------------------|-------------------------------------------------------------------------------------------------------------------------|
| Product Name | D-80N |
| Dimensions | 89.6 x 86 x 124.6mm |
| Weight | 398g |
| Operating Voltage | 20 ~ 53 VDC |
| Power | 6.5W (AVG) / 28.2W (Stall, lighting on) |
| Mounting | Downward / Upward |
| Gimbal | |
| Gimbal Type | 3-axis Nonorthogonal Mechanical Stabilization |
| Angular Accuracy | ±0.01° |
| Max Stable Tilt Angle | 45° |
| Controllable Range | Pitch: -145° ~ +60°, Yaw: ±360° constantly |
| Max Controllable Speed | 150°/s |
| Zoom Camera | |
| Image Sensor | 1/2.8-inch CMOS; Effective Pixels: 2.07M |
| Lens | Focal Length: 6.1~61.4mm (Equivalent focal length: 41.6~415.8mm) |
| | Aperture: f/1.8~f/2.6 |
| | HFOV: 48.8° ~ 5.2° |
| | VFOV: 28.6° ~ 2.9° |
| DFOV: 55.0° ~ 6.0° | |
| Resolution | 1920(H) x 1080(V) |
| Pixel Pitch | 2.9µm(H) x 2.9µm(V) |
| Optical Zoom | 10x |
| Equivalent Digital Zoom | 4x |
| Object Detection Distance | EN62676-4:2015 Person ^[1] : 927m; Light vehicle ^[2] : 1218m; Large vehicle ^[3] : 2595m |
| | Johnson Criteria Person: 10586m; Light vehicle: 32464m; Large vehicle: 69163m |
| Object Identification Distance | EN62676-4:2015 Person: 185m; Light vehicle: 244m; Large vehicle: 519m |
| | Johnson Criteria Person: 2647m; Light vehicle: 8116m; Large vehicle: 17291m |
| Object Verification Distance | EN62676-4:2015 Person: 93m; Light vehicle: 122m; Large vehicle: 260m |
| | Johnson Criteria Person: 1323m; Light vehicle: 4058m; Large vehicle: 8646m |
| NIR Laser Lighting | |
| Wavelength | 850±10nm |
| Laser Power | 0.8W |
| Beam Angle | 8° |
| Beam Diameter | 14m @ 100m |
| Effective Illumination Distance | ≤200m |
| Laser Safety | Class 3B (IEC 60825-1:2014) |

[1] Reference dimension of person: 1.8x0.5m. Critical dimension under Johnson criteria is 0.75m

[2] Reference dimension of light vehicle: 4.2x1.8m. Critical dimension under Johnson criteria is 2.3m

[3] Reference dimension of large vehicle: 6.0x4.0m. Critical dimension under Johnson criteria is 4.9m

AI Multi-object Detection & Tracking

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|---------------------------------|--------------------|
| Object Size | 16x16 ~ 128x128 px |
| Object Identification Delay | < 40ms |
| Tracking Speed | ±32 px / field |
| Tracking Deviation Refresh Rate | 30Hz |
| Tracking Deviation Output Delay | ≤5ms |

Image & Video

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|--------------------------|--------------------------------------------------------------------------------|
| Image Format | JPEG |
| Maximum Image Resolution | 1920 x 1080 |
| Video Format | MP4 |
| Maximum Video Resolution | Stream: 1920 x 1080 @30fps Recording: 1920 x 1080 @30fps |
| OSD | Time, Camera attitude, Carrier coordinate, Magnification level, Storage status |
| EXIF | Time, Camera attitude, Carrier coordinate, Resolution |
| SEI | Will be supported via subsequent firmware updates |
| Stream Encode Format | H.264 , H.265 |
| Stream Network Protocol | RTSP |

| | | |
|-------------------------------------------|--------------------------------|-------------------------------------------|
| Average Stream Delay & FPS ^[4] | OSD OFF & target detection OFF | Dragonfly: 190ms QGC: 230ms FPS: 30 |
| | OSD ON & target detection OFF | Dragonfly: 190ms QGC: 240ms FPS: 30 |
| | OSD OFF & target detection ON | Dragonfly: 200ms QGC: 250ms FPS: 30 |
| | OSD ON & target detection ON | Dragonfly: 200ms QGC: 250ms FPS: 30 |

Storage

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| Supported SD Cards | Supports a U3/V30 or above MicroSD card with a capacity of up to 256GB |
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Environment

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| Operating Temperature | -20°C ~ 50°C |
| Storage Temperature | -40°C ~ 60°C |
| Operating Humidity | ≤85%RH (Non-condensing) |

[4] Measured with the pod directly wired to a computer at 1x zoom ratio. When the zoom ratio exceeds 10x, video stream delay will increase and frame rates will decrease